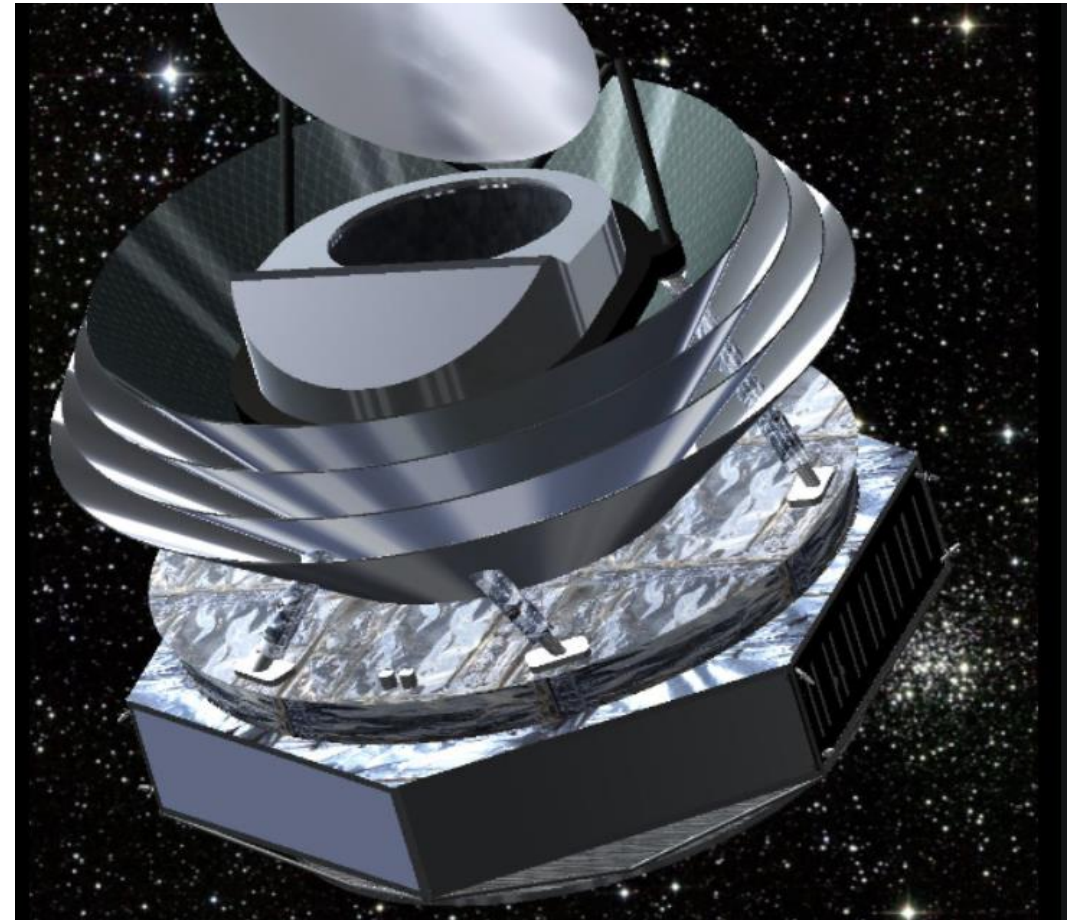


PICO delensing status

Update – 03.02.2022

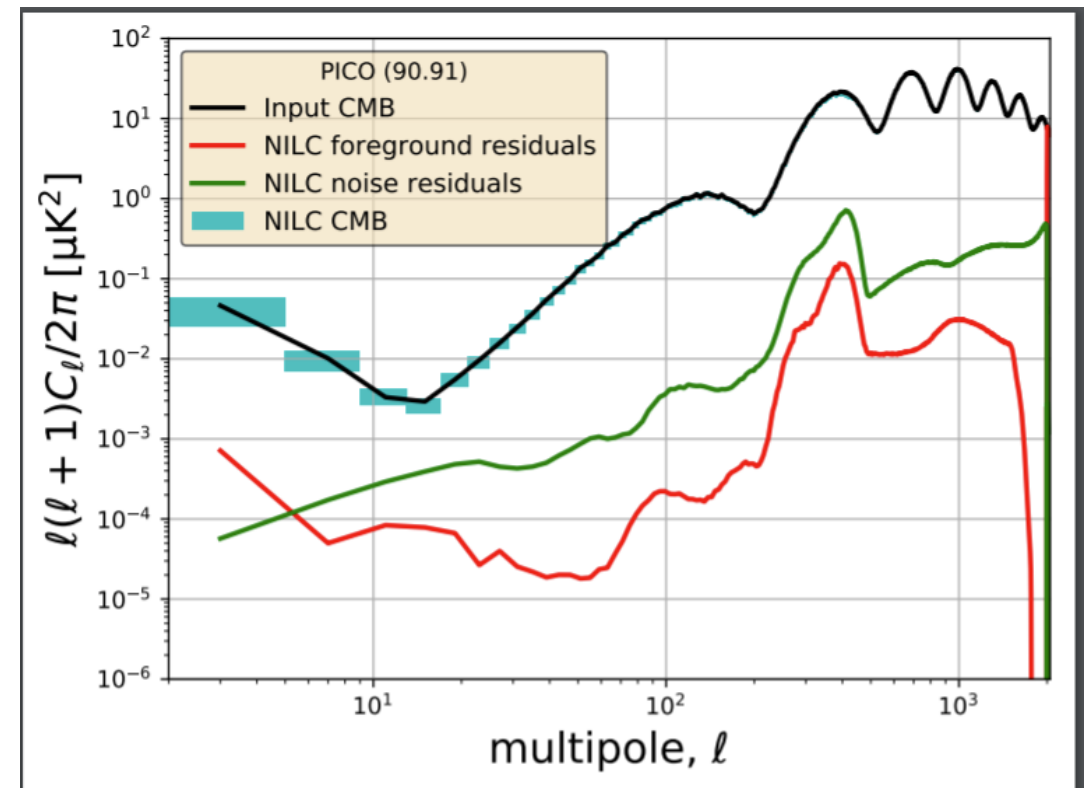
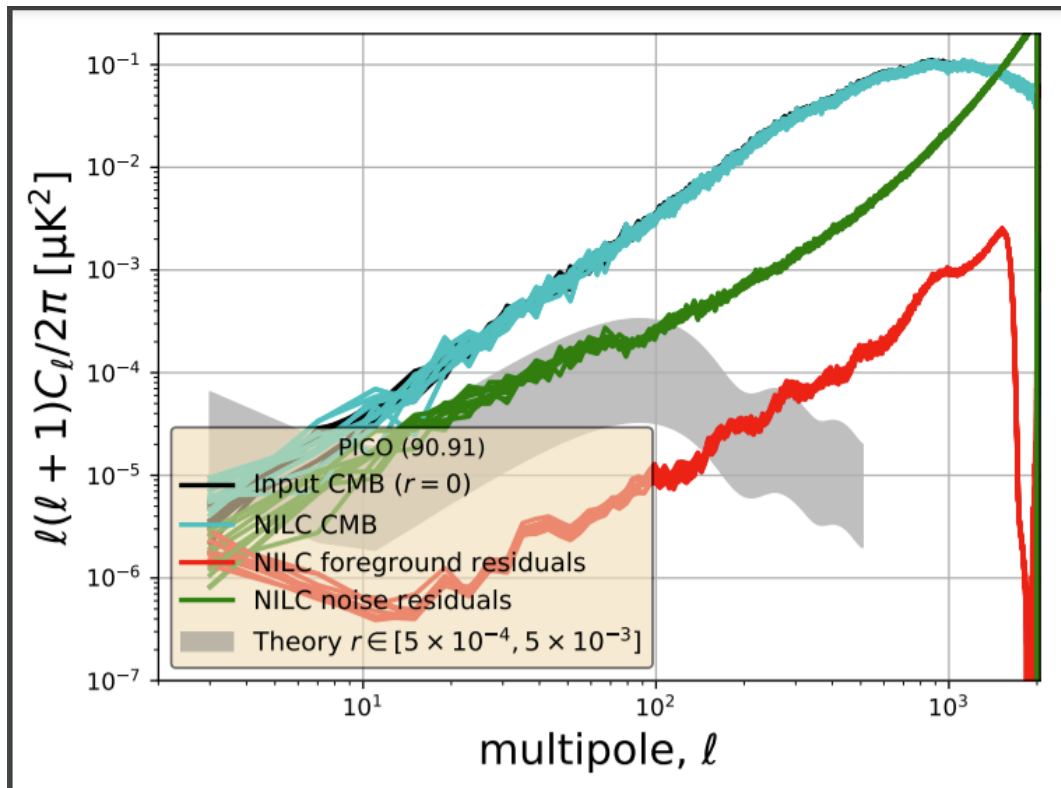
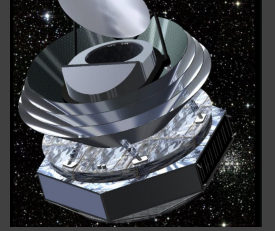
Sebastian Belkner, Julien Carron



Lenscarf

Data – 90.91

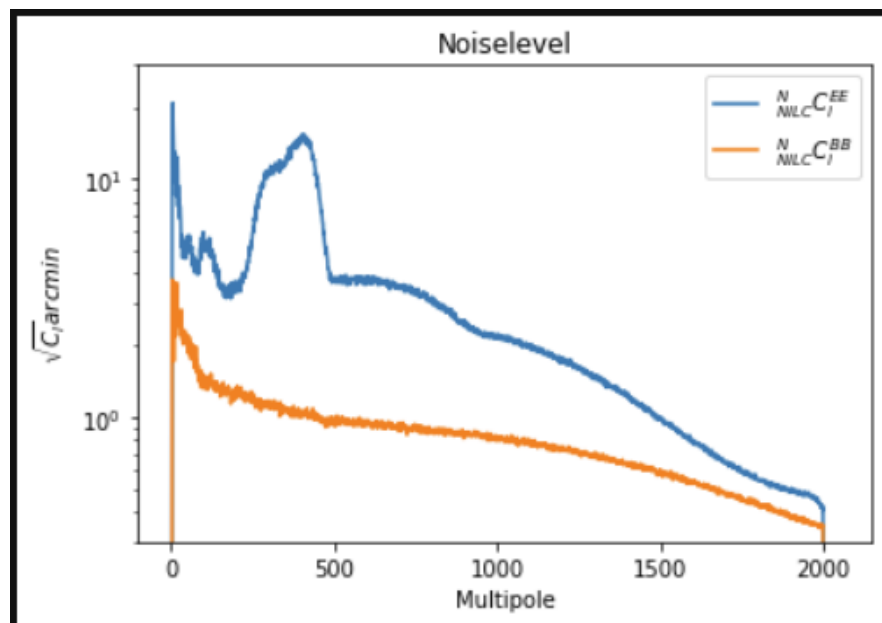
- FFP10 simulations w/ foreground
- E and B GNILC fg-cleaned maps @ nside 2048



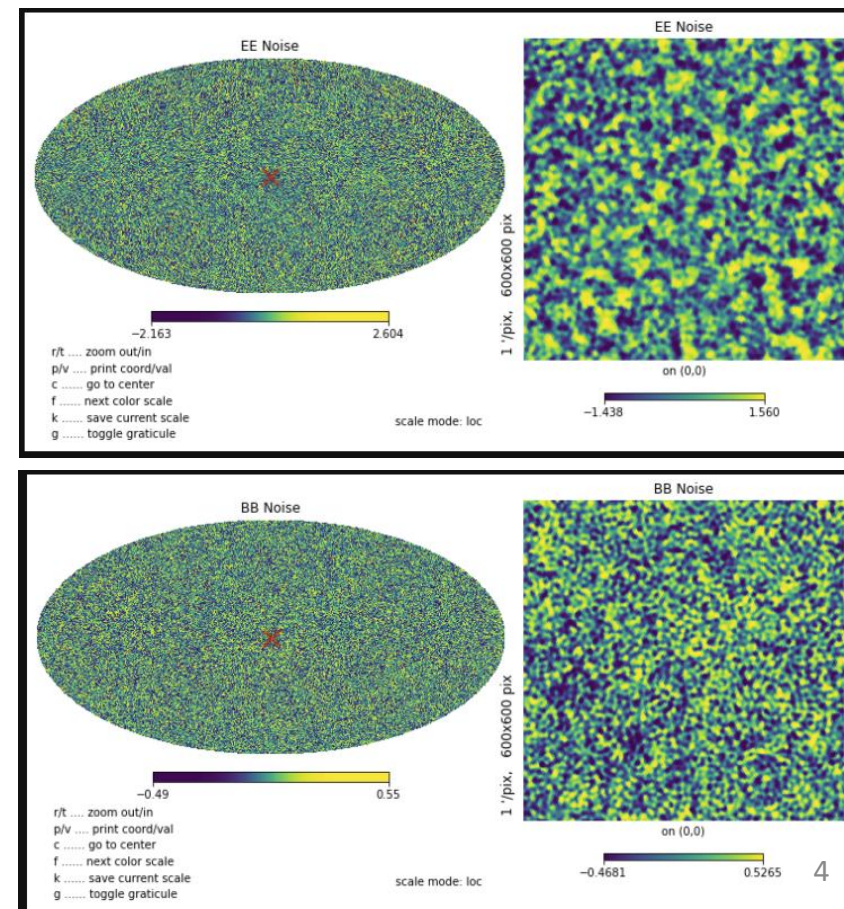


Check

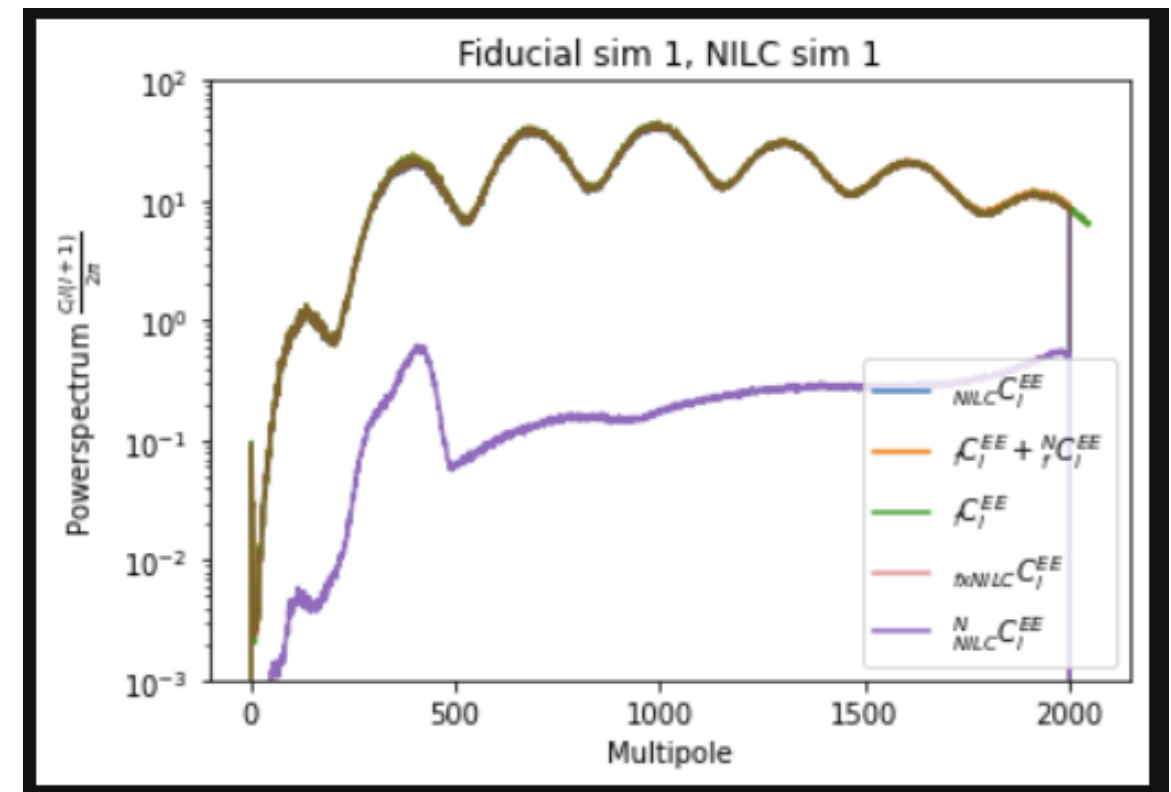
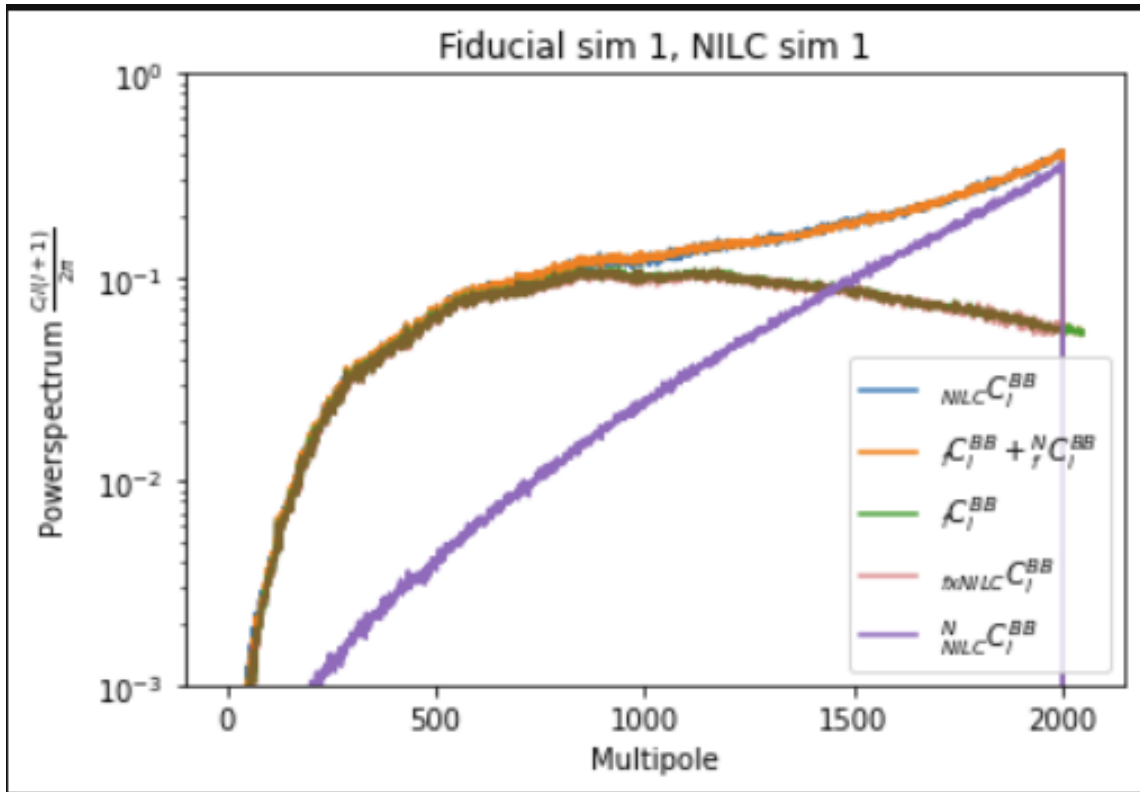
Noise



Iterative delensing, SB, JC



CMB



Summary



sim index is same as ffp10 sim index

8 arcmin beam

inside 2048 Pixelwindow function

E/B maps include noise



Delens

Results I



- QE / iterative delensing
 - QE : quadratic estimator
 - Iterative: MAP
- Vary E input
 - Ideal: E from ffp10 w/o added fg + Gaussian noise
 - Mathieus E: as is
- Compare to B input
 - pure ffp10 lens-BB
 - Mathieus: lens-BB + N_res + Fg_res

Delensing algorithm



- Lenscarf – MAP with iterative approach

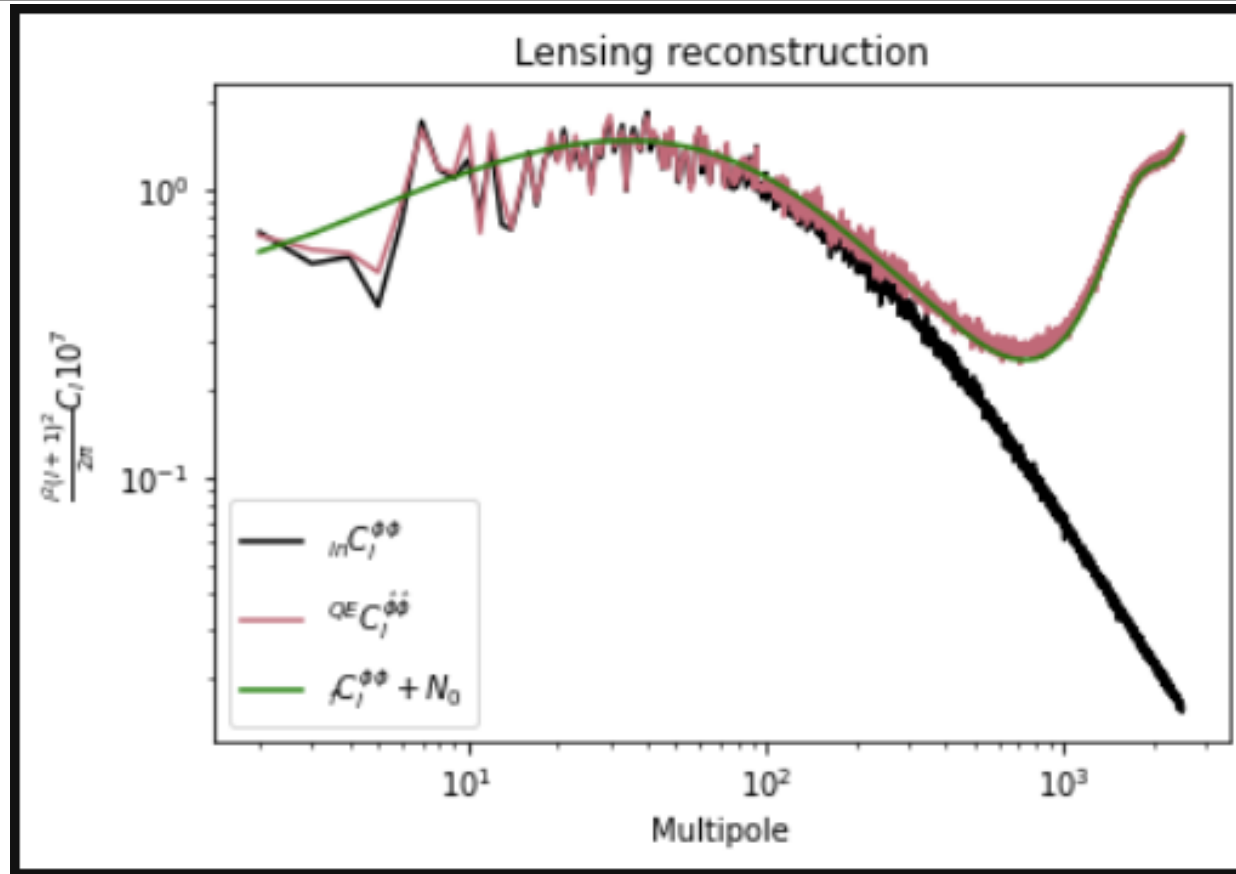
$$\ln p(\phi|X^{\text{dat}}) = \ln p(X^{\text{dat}}|\phi) - \frac{1}{2} \sum_{\mathbf{r}} \frac{\phi_{\mathbf{L}}^2}{C_{\mathbf{r}}^{\phi\phi}}, \quad (2.6)$$

$$g_a^{\text{tot}} \equiv \frac{\delta \ln p(\boldsymbol{\alpha}|X^{\text{dat}})}{\delta \alpha_a(\mathbf{n})} = g_a^{\text{QD}} - g_a^{\text{MF}} + g_a^{\text{PR}}, \quad (2.7)$$

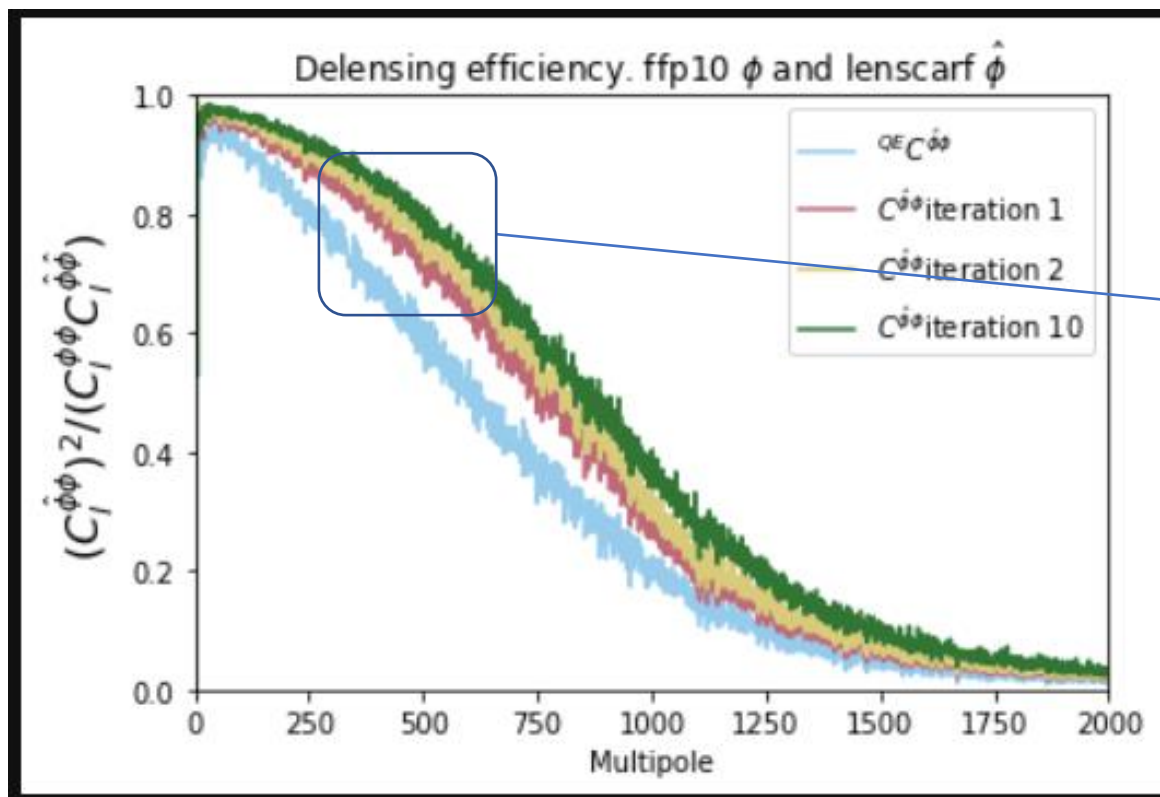
$$X_{\boldsymbol{\alpha}}^{\text{WF}} \equiv C^{\text{unl}} D^{\dagger} B^{\dagger} \text{Cov}_{\boldsymbol{\alpha}}^{-1} X^{\text{dat}}. \quad (2.11)$$

- Parameter choice
 - Drop E,B modes $< (30, 200)$

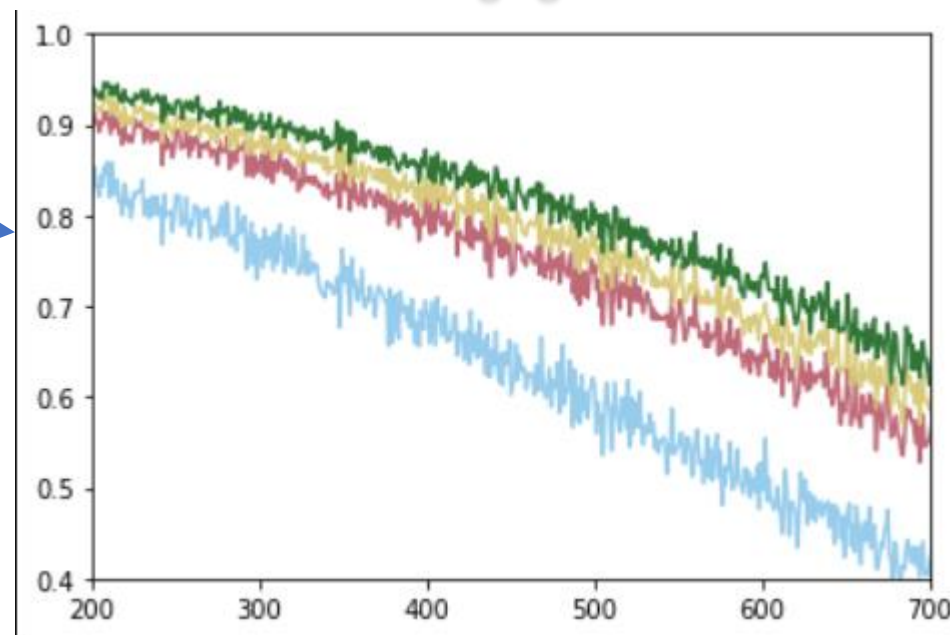
$C_l^{\phi\phi}$ - quadratic estimator



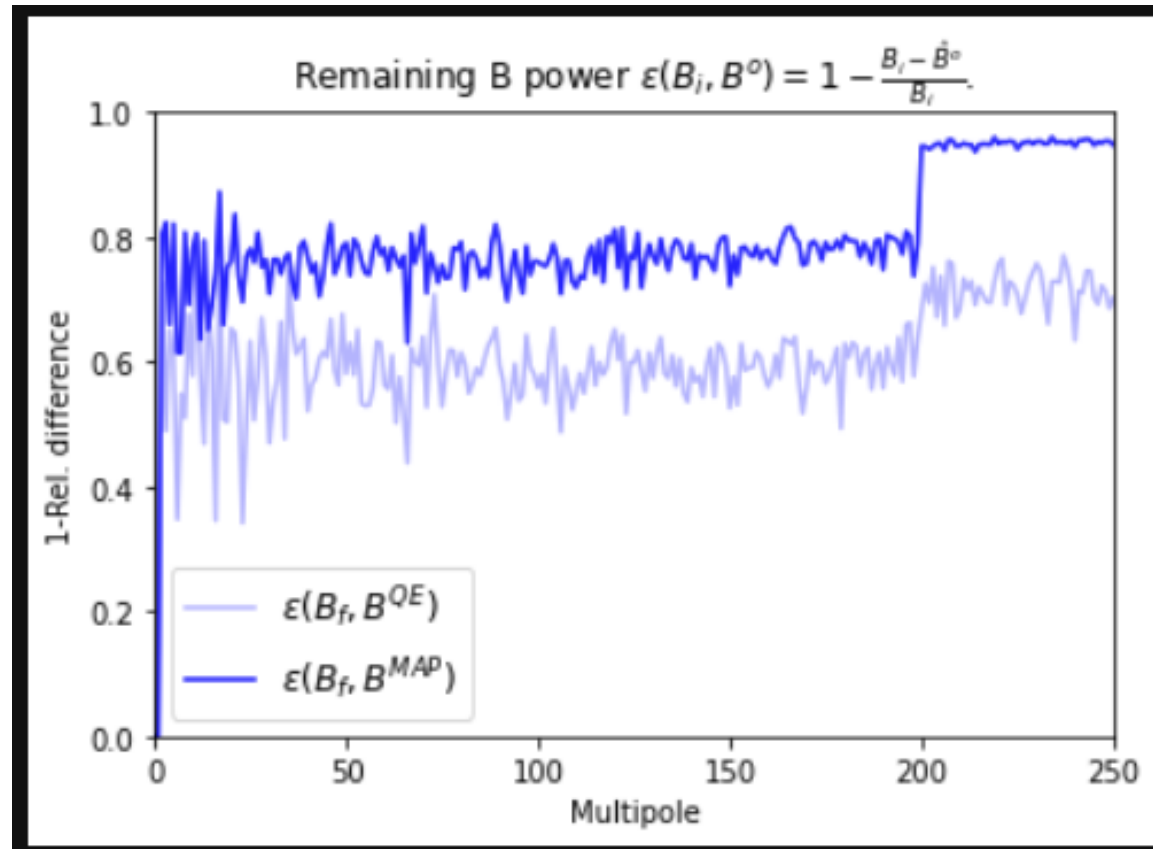
Improvement per iteration step



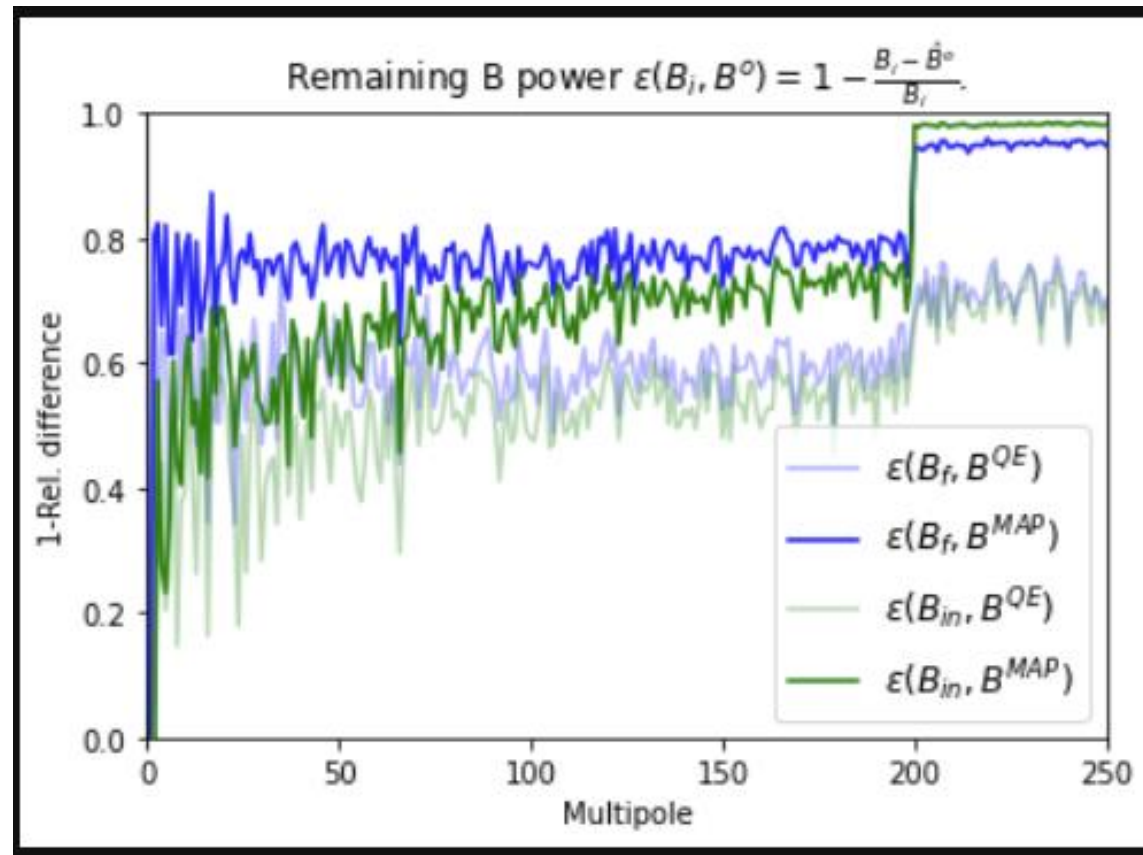
- It's converging



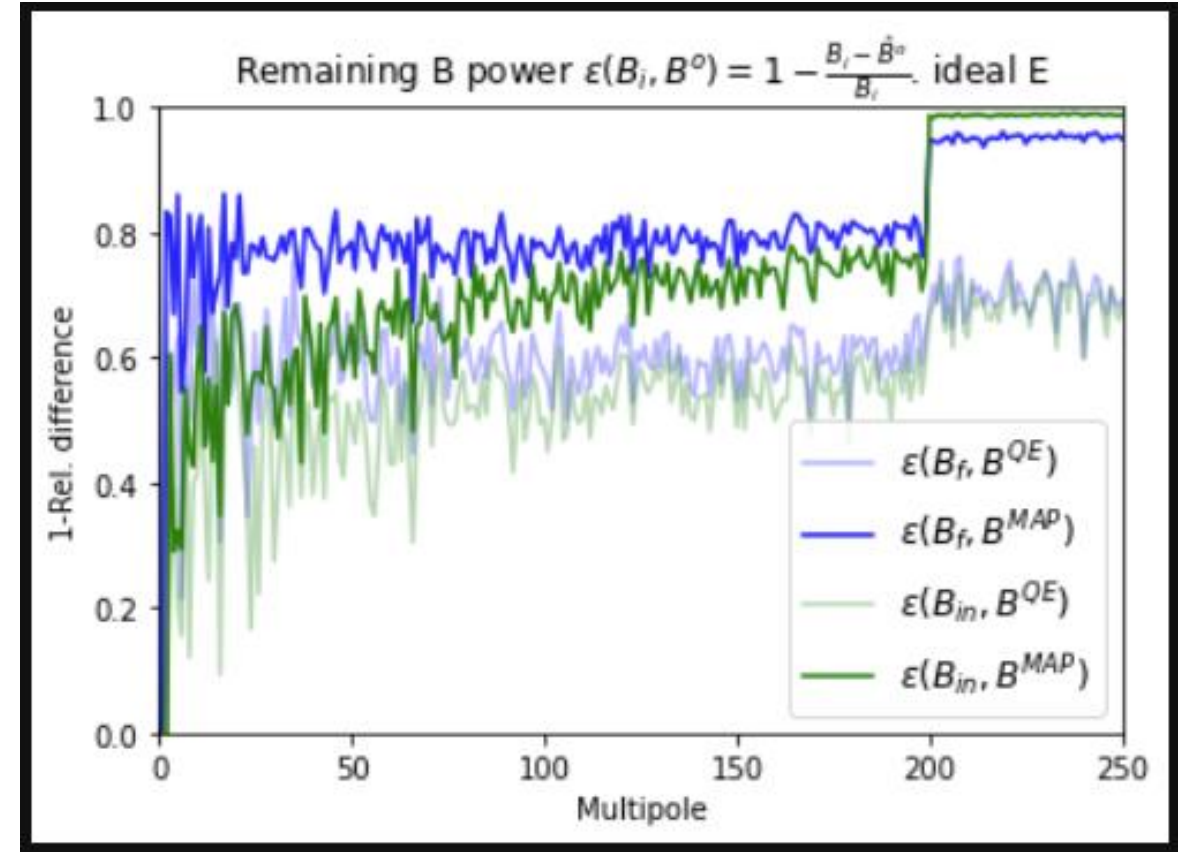
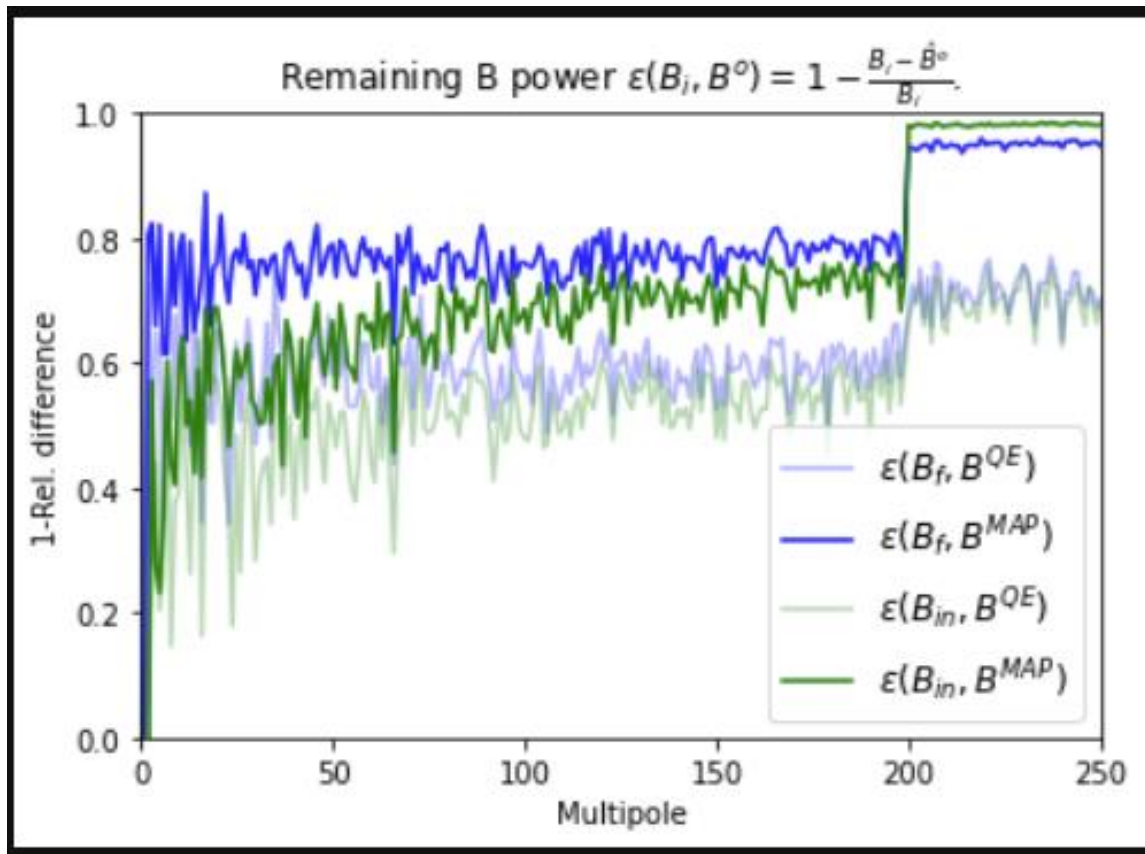
B mode after delensing



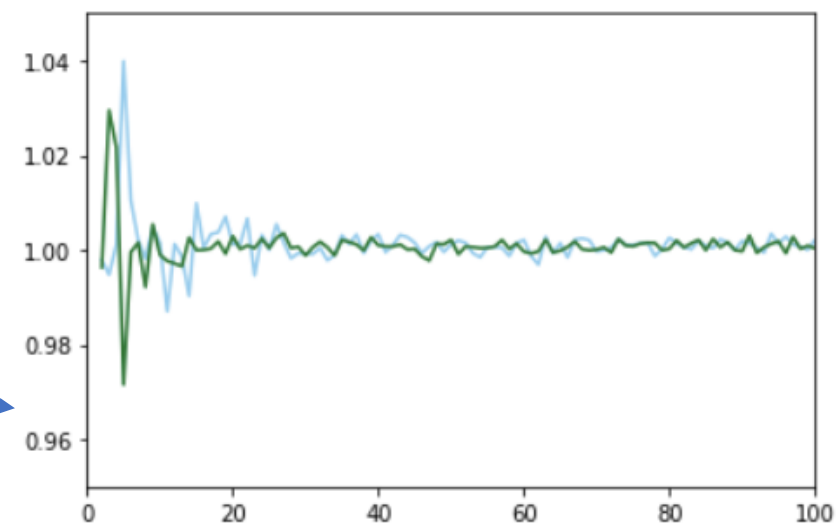
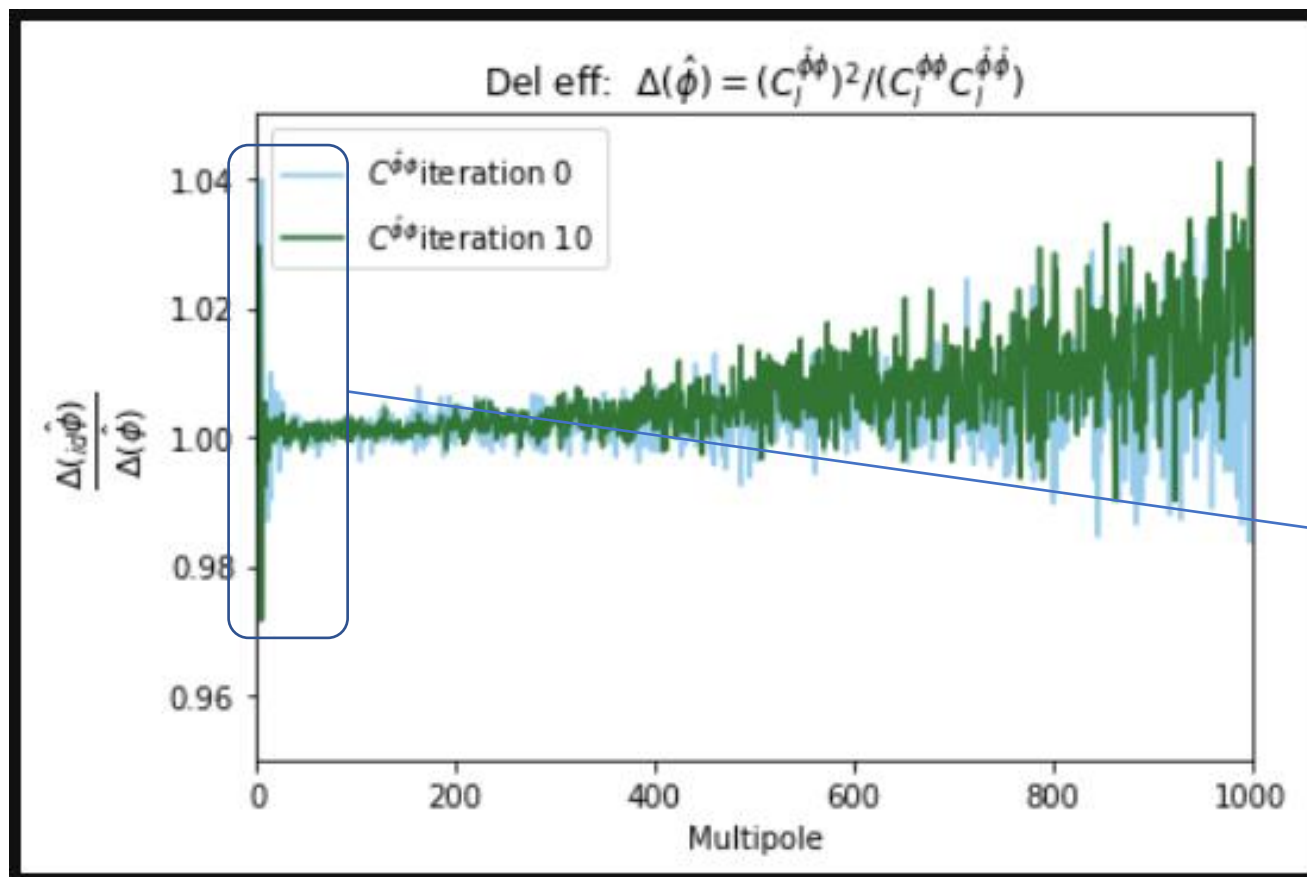
B mode after delensing



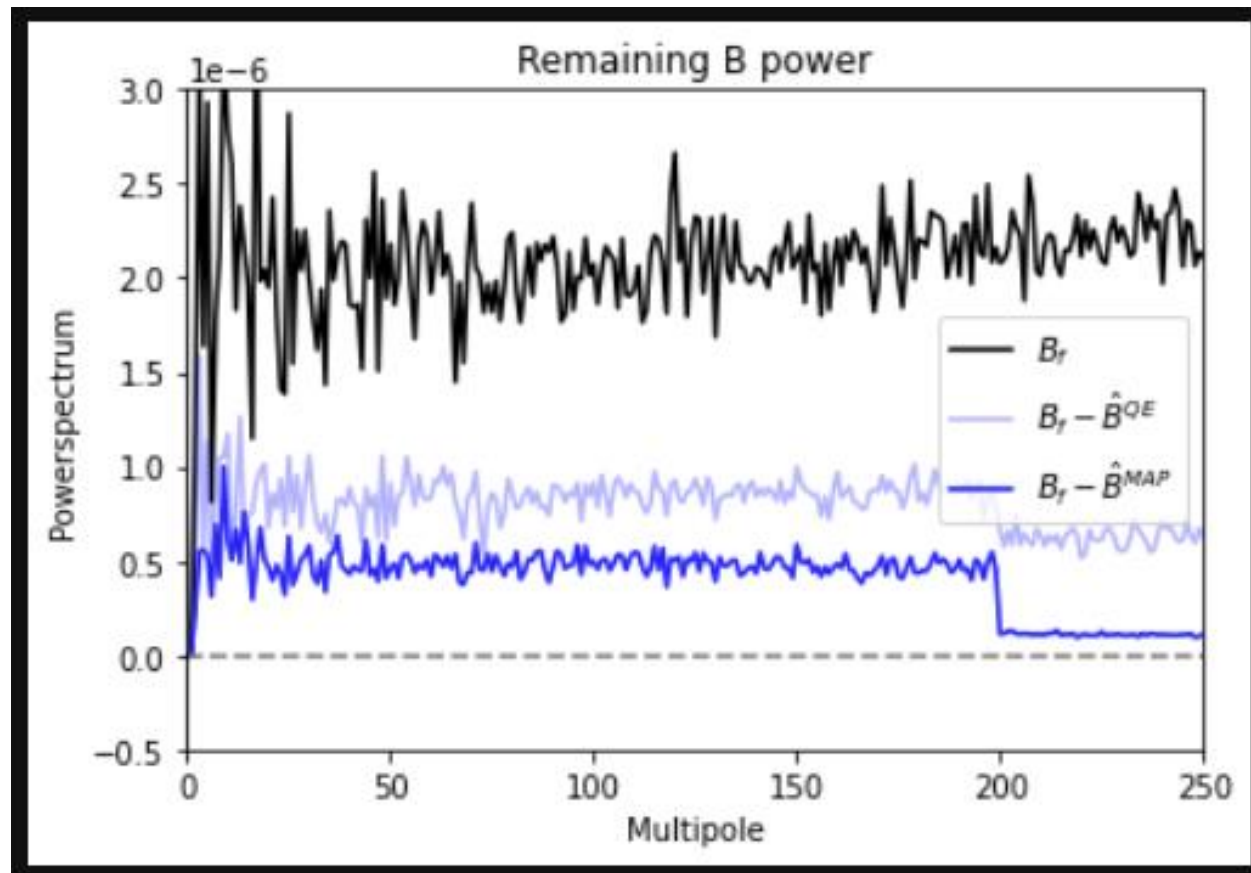
B mode after delensing



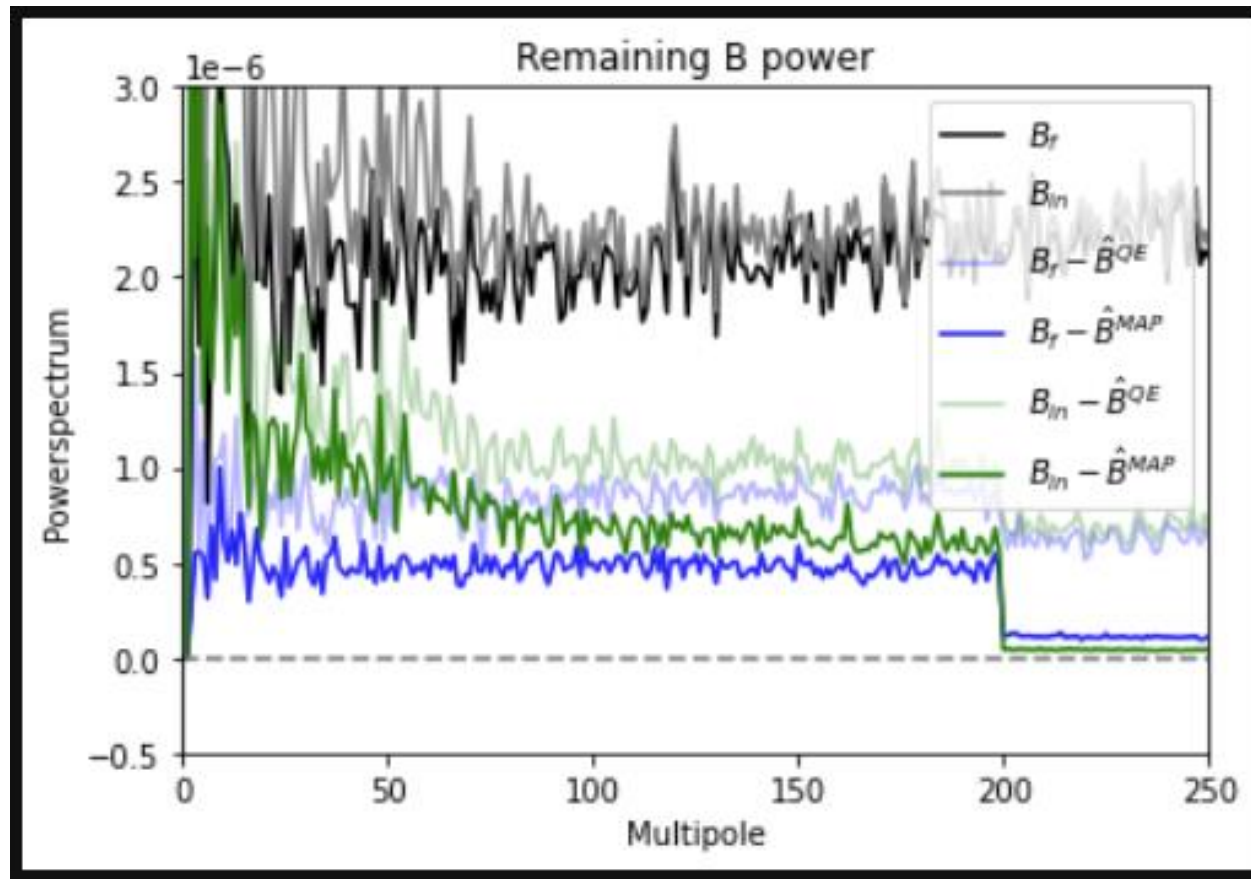
ideal E vs. sim E



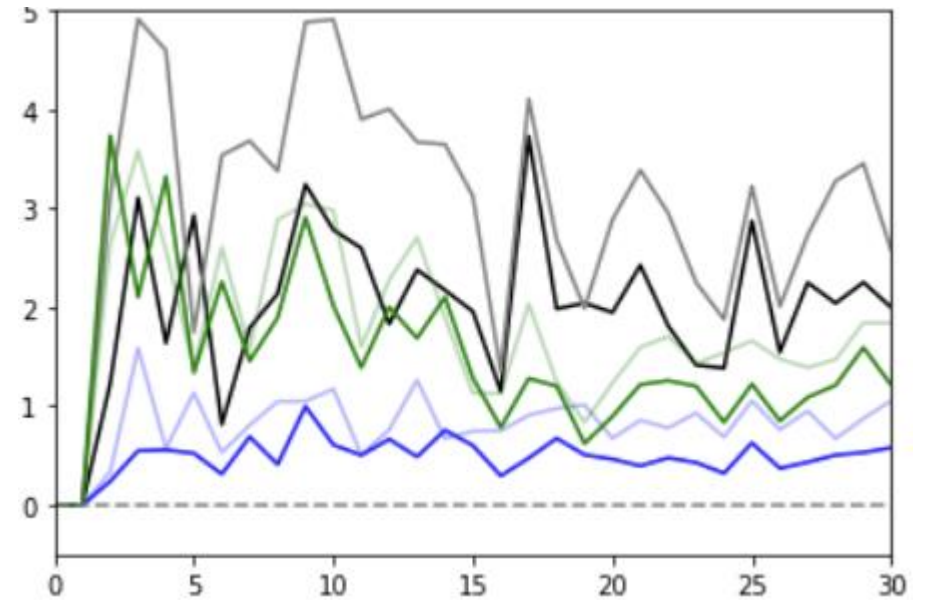
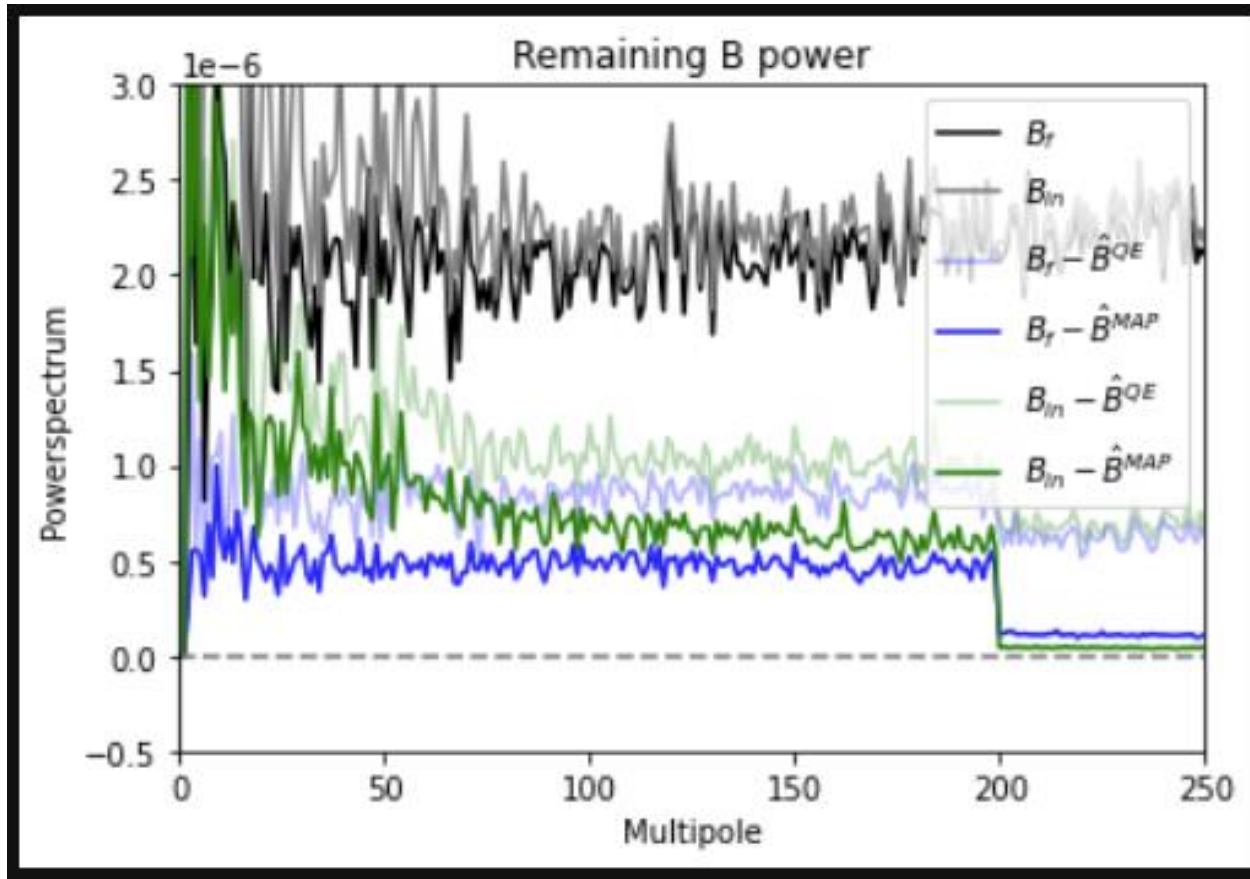
B templates



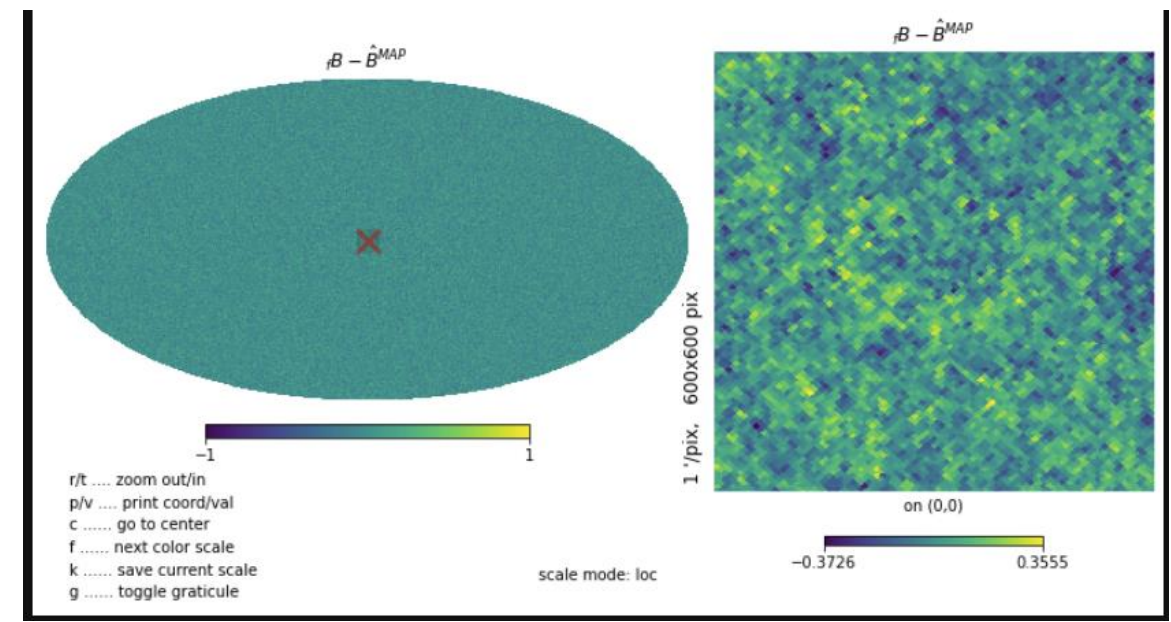
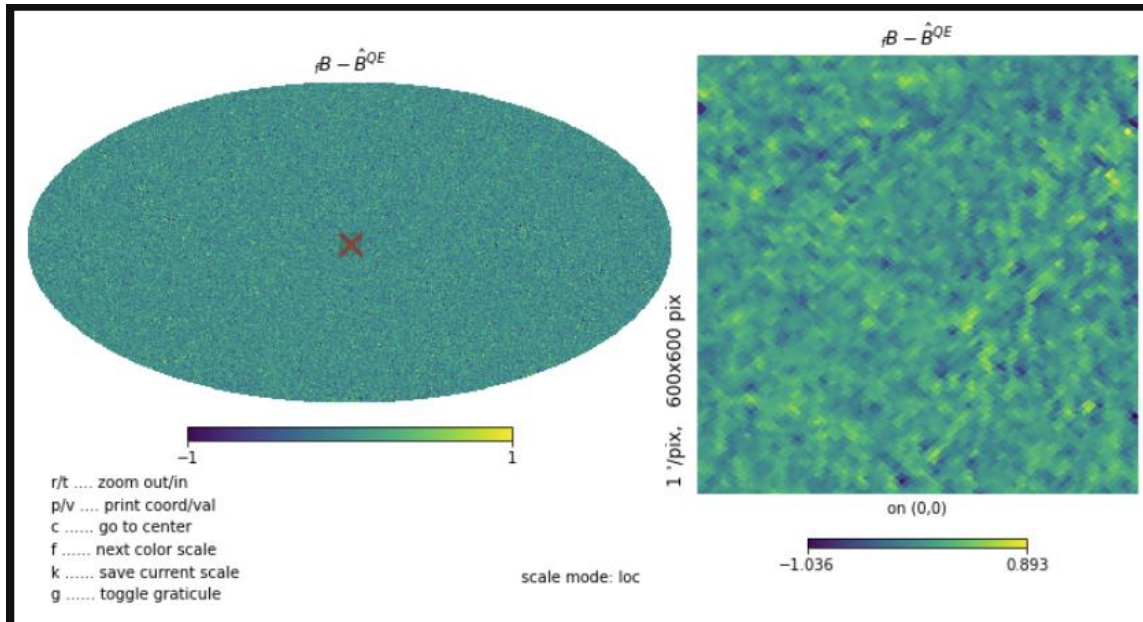
B templates



B templates

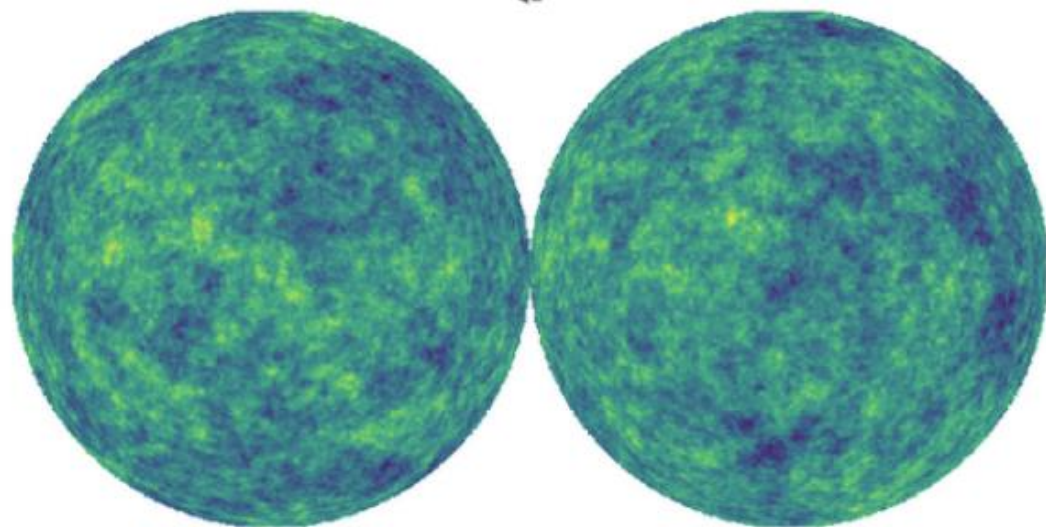


Remaining B, map level

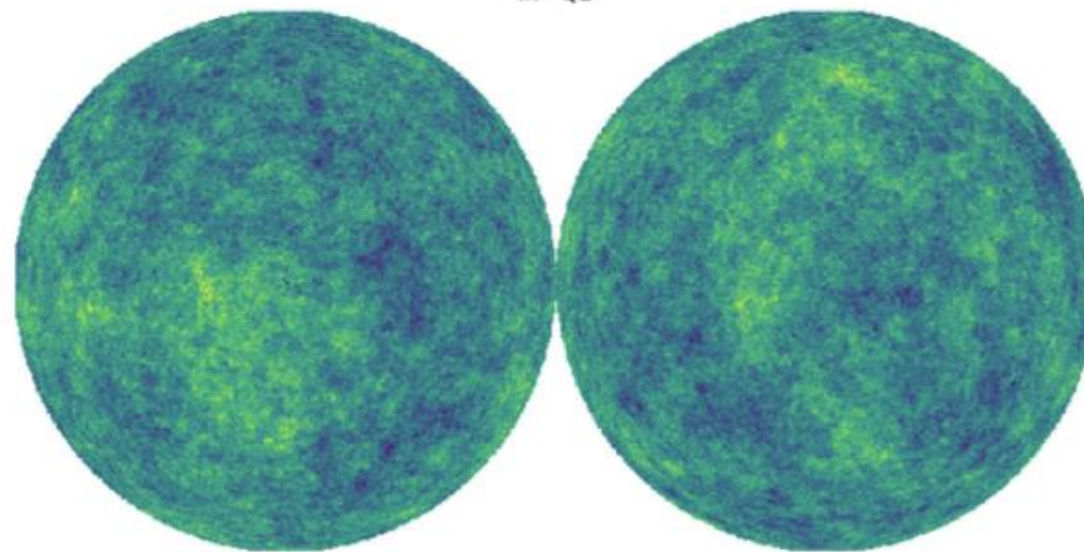




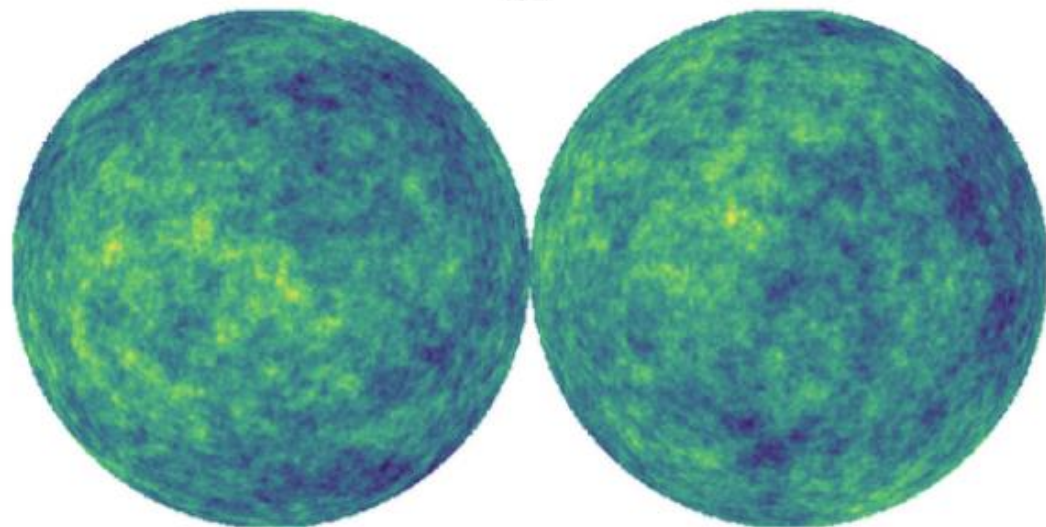
QE



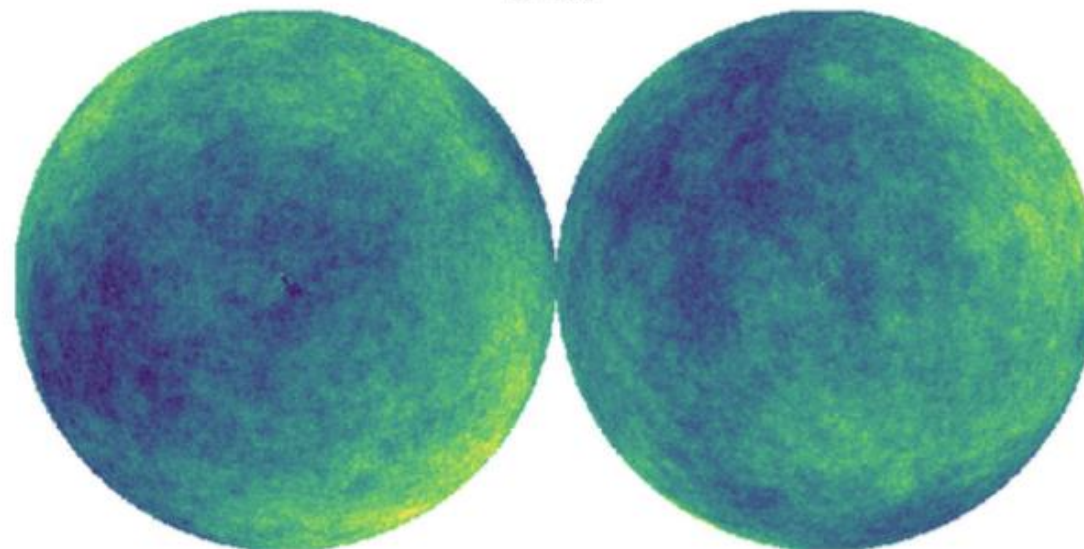
in - QE



MAP



in - MAP





Conclusion

Conclusion



- @ ell<200
 - 60% delensing using QE
 - 80% delensing using iterative delensing
- Delensing Ideal E $\sim$ Delensing Mathieu E

WHAT'S
NEXT

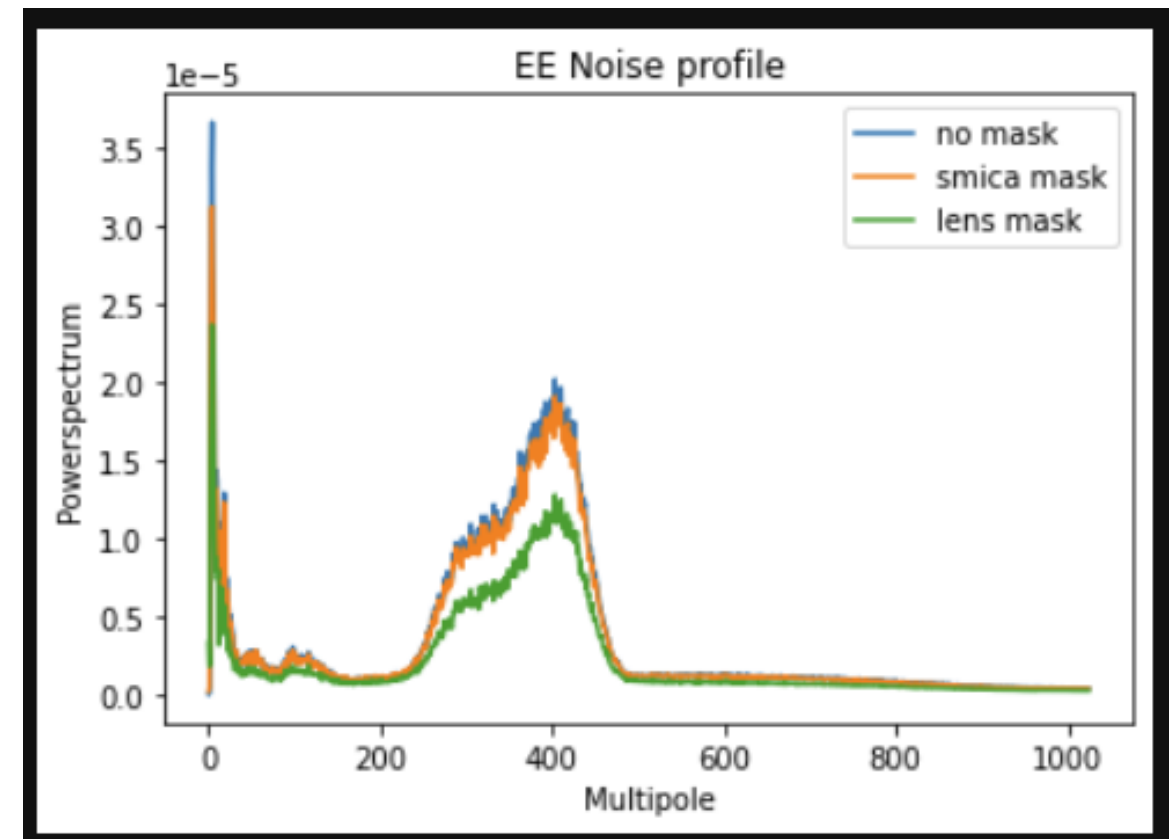
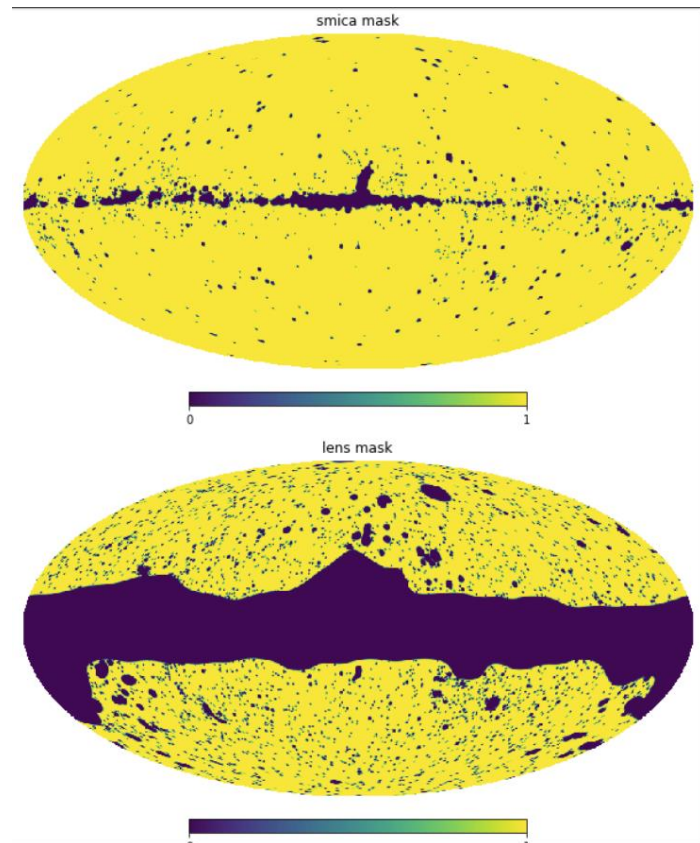


Whats next

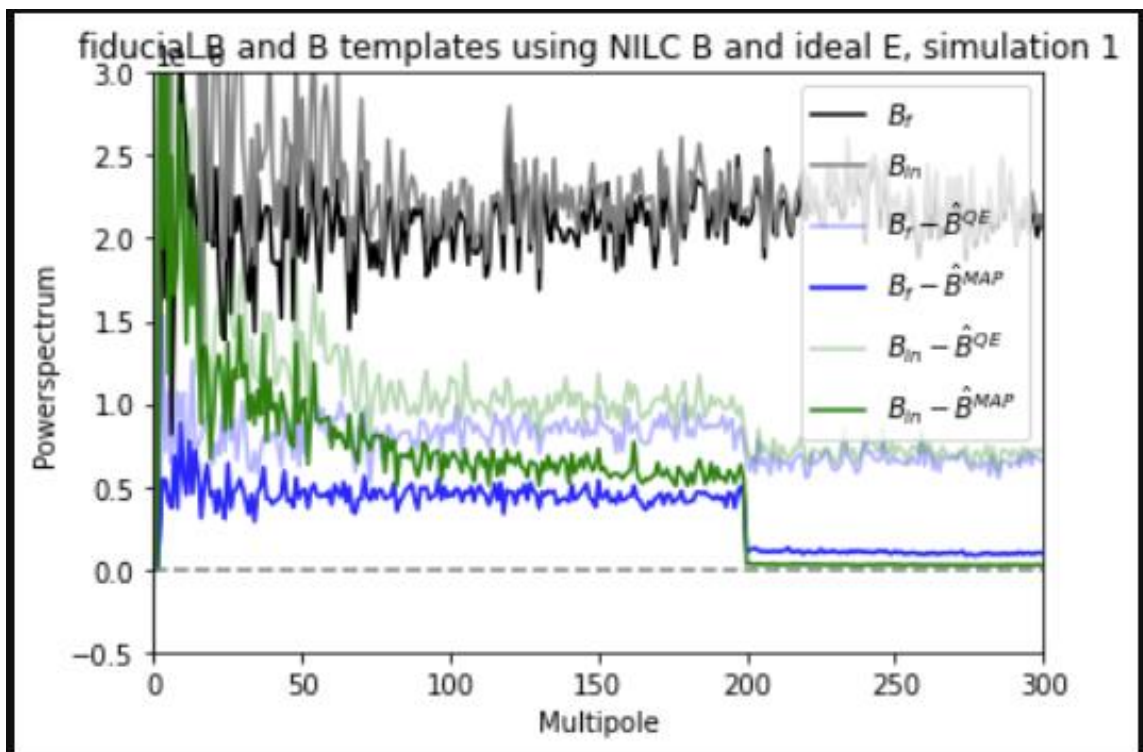
- Minor validations
- Run all simulations
- Integrate into Mathieus pipeline
- ?



Noise II



B templates



Forecast

