//-		Note: This Q330	was actua	lly installed	ed in January 2015	
	1 6 44 7	330 Surface Site with Wilan T :30 pm 1/14/2015 GMT	2014, but	fully contigur	ed (· · · · · · · · · · · · · · · · · ·	
	Date //4/1015	220 Camboo Cito anith Willow T	Vallaces (4.55)	Station_MAST_	lin server room	
	Local Date/Time: 2	130 surface site with whan I	Date/Time: 2	30 1/14/2015	admin	
	Field Team: Tanne	, Daniel, Vuk		•	building)	
					_ /	
	Equipment					
	Sensor S/N:	N/A	Sensor Type:	N/A	No Baler or sensor attached	
	Q330 BOS S/N:	0100000 A27A7705 B	Q330 TagID:	991	00	
	Q370 IP:	204.114.29.11	Wilan IP:		sensor attached	
	Clock S/N:					
	Baler S/N:	N/A				
	INSTALL SENSOR					
	Check that compass de					
	avoid sign errors)	ure below showing where the declin	nation marks is positi	on on this compass (cro	ess check against above to	
	avoid sign errors)					
				N/	A	
		5	F			
	Е	J U	→ W			
	_					
	, •					
	Guralp 3T					
		ndscaping timber to provide clearan	ce for this larger sens	sor		
	Sweep any dirt from the top of the concrete base Attach the alignment jig and use it to simultaneously level and orient the sensor					
	Lock feet of sensor Connect the sensor cable to the sensor and then to the DAS (leave enough slack to allow you to reattach the alignment jig)					
	Reattach the alignment jig and fill out the alignment table below (4 measurements). If initial orientation is off by more than 1 degree align and relevel before making final measurements.					
	Trillium or STS2		ements.			
All		rom the top of the concrete pad	on the concrete base f	or this sensor		
$\mathcal{N}(Y)$	Use a ruler and sharpie to scribe an alignment line on the concrete base for this sensorConnect the sensor cable to control box and sensorAlign the sensor using the mark and the alignment rad, level, repeat until level and aligned (fill out table below)					
	Align the sensor using the mark and the alignment rod, level, repeat until level and aligned (fill out table below) ALL SENSORS					
		"fire hose to run from sensor vault pull the DAS to control box cable		and connect both ends		
	Unlock masses	pair the Drib to control box cubic	unough the me nose	and connect both ends		
	Center masses Working with yo	our partner verify the sensor is func	tional with a stomp to	est		
	Install vault cove		1			
		g sandbags filled with dirt, mound	dirt ton top of vault c	over, and add mulch to	top	

DITOI		•	
DUGL	Hx	nerım	ent
		Der mi	CIL

Station Name	MAST
Station Ivallic	/ (

Use Brunton compass adjacent to sensor measurement jig, measuring North (N) and South (S). Reverse the jig and repeat recording the 4 measurements below. Record to your best guess of the nearest 0.1 degree. If orientation is more than 1 degree away from NS try to realign. For Trillium and STS2 sensors use left and right side of alignment rod

Brunton Left (N)	Brunton Left (S)	Brunton Right (N)	Brunton Right (S)

	Q330 Hardware Setup
	Install solar panels on post using brackets and wood screws.
(Reconfigure guy wires if necessary
\mathcal{A}	Place the dog house near the solar panel pole with the door facing downhill to allow water to drain
NIN	
- 1	Install GPS on top of pole (must see the sky)
(Install Wilan radio on the pole (make sure the antenna is on the side facing Yates)
	Run GPS and network cables and connect to Q330 (do not bundle up until testing is finished)
	Connect the baler to the Q330
	Power system tests:
	Initial battery voltage (V) N/A
	Solar panel output test:
	Sun condition when tested (circle one): (a) sun on panels, (b) cloudy, (c) sun on panels at low angle
	Panel 1 output (V) N/A Panel 2 output (V) N/A
	Panel 2 output (V) N/N
	Equipment power up:
(Make sure power box is set for sealed battery mode
NIAI	Plug battery into power box. Record voltage showing on LCD display (V) Connect both solar panels to power box. Record voltage on display (V)
1.0	Connect both solar panels to power box. Record voltage on display (V)
Z	. ✓ If all looks ok, connect the Q330 to power (Note with Guralp unlock cannot happen till now)
	✓ Check here when the GPS LED goes yellow
	Q330 Operations with the Clie (program Q330B147 on the SONY Clie PDA)
	Clone the program into the Q330
	Commands->Cloning
	>Select file to clone based on sensor type
	>Station names
	>Palm overrides 330
	>"Check" Edit/Verify >IP Addresses
	>Palm overrides 330
	>"Un-Check" Edit/Verify
	!Send
	>Station Names
	>DP4 >New
	!Enter current station name (All CAPS and up to 5 letter/number characters)
	!Ok
	101
	Views -> Data Recording -> DP *Station name MAST (SENSOR TYPE)
	Views -> Data Recording -> DP *Station name MAST (SENSOR TYPE)
A 1/A	Views -> Data Recording -> DP *Station name (SENSOR TYPE) Note: DP3 station name should correspond to sensor type.
NIA	Views -> Data Recording -> DP *Station name MAST (SENSOR TYPE)

	Date 1/14/2015	Station	MAST	3
	□ SENSOR Unlock Procedure			
	CMG-3T: Attach extra power to 3T BOB. Use the BOB to test if the se Enable Buttons for about 10 seconds. Watch the LED light (4 use.)	l-6 blinks in ~3	3 sec = Locked: indicates OK t	to
	Next, unlock the sensor. Press and hold both the <u>Unlock</u> and buttons when the LED light illuminates (2 blinks and solid re TURN OVER	Enable Button d indicates unl	s for about 10 seconds. Release locking.)	3
	STS-2: Use an STS-2 screwdriver to smoothly unlock all 3 elements. using the button on the host box.	Give the STS	-2 and initial centering pulse	
	Views > Sensor: !Center A (STS-2)			
	*Ant. Current: 75 m A *Input Volts: 12.6 V *Ant. Current: 4mA *Temp: 22°C *Q330 SW Vers: 1.146 *Last Boot: 1/14/2015	*Last Re	1 sun, >11.5 no sun) sync: \(\lambda / \lambda / \lambda / \lambda / \lambda	Filled out
	Views -> Clock: *Last Lock: $22:03:17$ 1/19/2015 *Phase *Clock Quality: 100%	error:	<u>rs</u>) '01.
λ (/	*Clock Quality: *GPS Date: *GPS	/ 7 /2015 <u>N</u> *Longitu .5 volts)	(given in DD/MM/YYYY) (ade: 103° 45′ 4.331″ (w	Filled out > 0.1 1/17/2015
10()	P(1333333			
	** If the Boom Positions are out – recenter sensor: Views ->Sensors!	Center A		
MA	☐ Views ->Quickview ->chan 1,2,3 -> !Start Stomp test: ch 1: ☐ OK ch 2: ☐ OK			
(~(),	ch 3: ☐ OK (stomp seen?) -> !Stop Write values:			
NIA	ch 1: maxmin RMS ch 2: maxmin RMS ch3 maxmin RMS (Values should be ~10,000 counts)			
N/A	☐ Status -> Data Port Txfr -> Data4 *Packet buffer used (increasing?) YES	S NO		
NA	☐ Commands ->Baler Cmds Turn on baler power control ☐ !Send Baler Command (Baler should turn on) Do NOT u Note: If the baler times out BEFORE finish	ise ATTN butt		
ILA		ES NO		
<i>V</i> ,	*Data packets sent	_		
	NOTE: If the Q330 does not transfer data to the Baler try clearing the Baler "button in until the light turns solid red (~5 sec). Release the button and then, a Attention button once to shut down the Baler. Repeat the process once more as	fter the light be	egins to flash green, press the	1
	☑ Status->General*Total ReSyncs950			
NIA	☐ Views ->Sensor: *Boom Positions (less than +/-15, i.e. less than +/-1.5 vol	lts)		
, v	1233 App ->Make Docfile !OK to default filename Conf-YrMoDy-Q330			
NW	☐ App ->Make Docfile !OK to default filename Conf-YrMoDy-Q330			
	SITE NOTES (Anything strange or notable)			

N

Checklist

Par	erw	ork
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Completed pages 1-3

Sensor

- _Compass declination set and recorded
- Oriented
- Level
- Feet locked

Power system

- Battery terminals tight
- All power box connection tight
- Any external power cables to box secured from rodent damage
- Cables in the air have drip lines
- No cables are on the ground without protection
- SOLAR: panel boxes closed
- AC: battery minder plugged in powered

Q330

- ✓ Completed paperwork on pages 1-2
- X Acquiring data
- ✓ All unused connectors capped

Site

- Multiple layers of plastic on top of vault
- Plastic configured to not collect water around sensor vault
- Vault well covered with sandbags and dirt (6 inches minimum)
- Cables all secured
- Dog house door is secured
- ___Cable entry plugged with plumber's putty