

Mu2e Solenoids

Michael Lamm L2 for the Mu2e Solenoid July 27, 2015



Mu2e Solenoids

- Perform many functions in the Mu2e Experiment
- One continuous field, generated by 3 unique superconducting solenoid systems
- Need superconducting magnets to achieve required fields
- Challenges associated with superconducting magnets
 - Cryogenic environment
 - LN2 and LHe
 - Large stored energies (over 100 MJ)
 - Has to be removed or absorbed once a quench occurs
 - High currents (many kA's)
 - High voltages when a quench occurs
 - Large magnetic forces (100 Ton axial forces between magnet elements)
 - Large material stress (on the order of 50 MPa)
 - Yet it doesn't take much of a disturbance to cause a quench...
 - ~100 mJ

Detector vs. Accelerator Magnets

Accelerator magnets (for circular accelerators)

- Dipoles and quadrupoles, (sometimes solenoids) Small aperture (100 mm), long (can be 20 meters)
- Often sets limit for beam energy (tunnel radius fixed) so designed for high fields → small operating margins
- Magnets operated in both ramped and DC modes
- Coil immersed in liquid helium
- Many interchangeable magnets, pool of spares, relatively easy to swap out if one fails

Detector magnets

- Solenoids, toroids very large apertures (meters) and long
- Large volume → coils usually conduction (indirectly) cooled
- Magnets operated in DC mode only
- One of a kind, non interchangeable therefore designed with large operating margins

Mu2e Magnets are somewhere in between (but more like detector magnets)

Interesting facts about charged particles in a solenoid field

Mu2e field is generated from a system of solenoid rings

- Charged particles execute a helical orbit in a uniform Solenoid Field
 - Radius proportional to Pperp
 - Radius Inversely proportional to Bfield
 - Helix sense given by particle charge

Non-uniform field

- With an axial gradient, Bz increasing,
 - Radius of helix decreases
 - Vperp increases, Vparallel decreases (V constant since no work)
 - under certain conditions the particle can actually reverse direction (magnetic mirror) Consequence of Div B = 0
- Conversely, if field decreases
 - Vparallel increases relative to V perp
- We use this to increase acceptance and minimize backgrounds



 See "Classical Electrodynamics"
2nd edition JD Jackson section 12.6





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Non-uniform field II

- In a "toroidal" field (with a horizontal orientation, and direction normal to the toroid is direction "s")
 - Particles tend to follow the field lines.. Helical centroid follows "s" direction of a curved solenoid…
 - The centroid of the helix will drift vertically, proportionally to sign and momentum
 - Problem for Toroidal Tokamaks
 - We exploit this to eliminate backgrounds

 See "Classical Electrodynamics" 2nd Edition JD Jackson section 12.5

Mu2e Experiment

- Three solenoids, provide magnetic field for experiment
- Strong axial gradient. Reflect and focus (move along) π/μ's into muon transport
- 55 Ton Heat and Radiation Shield to intercept target secondaries



Mu2e Solenoid Scope



- Cryo distribution box
- Power Supply/Quench Protection
- Field Mapping
- Ancillary Equipment
- Installation and commissioning

Operational Requirements

- Reliable superconductor operation at full field life of experiment
 - Large temperature margin (>1.5K) and Jc margin (>30%) typical of detector solenoids.
 - Complex thermal mechanical design to obtain and maintain desired field
- Individual operation of magnets and cryostats
 - Cryostats cooled down and powered independently
 - Individual magnets do not rely on mechanical support of adjacent magnets
- Cryogenic operation
 - Liquid helium Indirect cooling
 - One Fermilab Satellite refrigerator for steady state operation
- Operation due to radiation damage
 - 7 MGy over life of solenoid. (irreversible damage limit of epoxy)
 - Conductor and stabilizer to operate for 1 year at nominal beam intensity without loss of performance, can be repaired by room temperature anneal

Solenoid Design Features

Solenoid have common design features:

- Consist of multiple "solenoid coil modules". Use AI-stabilized NbTi cable wound either in the "easy way" or "hard way". Length and # of layers to achieve desired field.
- Module has an outer support structure made of AI 5083-O to manage the forces. Cooling tubes, electrical connections located on the outer surface
- Coils are "indirectly" cooled with liquid helium. Helium thermally connected to coil through aluminum straps and through structure
- The shells are bolted together to form a cold mass assembly.
- The coil modules are installed inside of cryostat using axial and transverse supports.

TS Module Overview

It is the basic building block of Transport Solenoids

- TSu TSd TSd Control Co
 - Modules bolted together to form required "S" shaped geometry. Geometry defines the magnetic field

- Typically 2 superconducting solenoid rings per module
- Outer aluminum support shell
- Coils indirectly cooled with LHe
- 27 modules in total
 - 13 in TSu
 - 14 in TSd



Design – TS Module



Phase diagram for ² NbTi

- From "Superconducting Magnets", Martin N. Wilson
 - Superconducting condition when conductor is below "critical surface"
 - Conservative operating conditions using state of the art NbTi Conductor
 - 5 K
 - 5T
 - 2000 A/mm^2



Fig. 1.1 Critical-current surface for a commercial superconducting alloy of niobium-titanium. (Based on recent measurements at 4.2 K, together with earlier measurements at variable temperature by Hampshire, R., Sutton, J., and Taylor, M. T. (1969).)



NbTi Rutherford cable with aluminum co-extruded stabilizer

- SC content sized for Specific Magnet Requirement for Current and Temperature Margins
- TS/DS: 99.998% aluminum for high electrical and thermal conductivity
- PS: use special Ni Doped Aluminum Alloy developed for Atlas Central Solenoid, for high strength and high conductivity
- ~75 km of conductor required for project
- Prototype conductor program successfully completed, production program in progress

Magnet Quench

- A quench is an abnormal termination of magnet operation that occurs when part of the superconducting coil enters the normal (resistive) state. (Wikipedia)
- Resistive state usually occurs due to a local rise in temperature past the critical surface due to a mechanical disturbance (also beam induced heat...)
 - If disturbance is small enough, thermal conductivity and electrical conductivity may be sufficient to recover
 - Otherwise... runaway (quench) condition
 - Potentially very dangerous state for magnet
 - Must have very reliable quench detection and subsequent plan for dealing with stored energy

Design magnets to operate well below Critical Surface



TS Prototype Coil Module



TS Prototype Coil



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TS Prototype Insertion into Cryostat at CHL



Future Mu2e-like experiments....

Need to significantly increase muon yield....

- More intense proton beam.. more heat/radiation to production solenoid (PS) from production target secondaries
- Higher field PS to improve collection efficiency
- → More stress on PS!

If we are limited by our present PS only options are to

- Use better (also more expensive) secondary beam absorber (probably Tungsten)
- Lower LHe temperature
 - Counteract increased heat load from secondary
 - Perhaps allow us to increase current
- Eventually we will be limited by rad harness of epoxies and insulation and aluminum stabilizer

May consider a new PS made with High Temperature Superconductor (HTS) which can operate at a higher temperature

Additional slides

PS Design - cold mass suspension system



- Axial suspension:
 - 6 asymmetric pairs of Inconel-718 rods;
 - Belleville springs at each rod's end to compensate the thermal contraction.
- Radial suspension:
 - 4 pairs of Inconel-718 rods at each end;
 - Half of the rods is loaded through the Belleville springs to compensate the thermal contraction.

Design: vacuum vessel & support frame



- Provides insulating vacuum and attachment points for all components (in and out);
- Transfers all loads to ground:
 - Cold mass and LN₂ shield weight through the radial supports;
 - Lorentz forces through the axial supports;
 - HRS weight through the inner shell (~55 tonnes);
- Provides interfaces to:
 - HRS upstream, downstream;
 - Transport solenoid;
 - Transfer line;
 - Instrumentation line;
 - Vacuum system.

Design: Detector Solenoid (DS)



- 1.8 m Aperture Operating Current ~6kA
- Gradient section 2T→ I T field
- Spectrometer section 1 T field with small axial gradient superimposed to reduce backgrounds
- 11 Coils in total
 - Axial spacers in Gradient Section
 - Spectrometer section made in 3 sections to simplify fabrication and reduce cost
- PS uses similar fabrication technology

General Solenoid Requirements

- Magnetic field requirements, described in the Mu2e Technical Design Report and in supporting documents, are complex. Generally speaking field must meet the following:
 - Straight Sections
 - Negative monotonic axial gradient to prevent trapped particles. (potential source of backgrounds)
 - Toroidal Sections
 - Matched to central collimator geometry for muon momentum selection
- To verify that the solenoid system meets the field performance standards
 - Generate field maps within coil fabrication tolerances
 - Field Maps are vetted with collaboration for muon transmission, background generation and tracking efficiency and resolution

Solenoid Schedule CD-3a Conductor

CD-3b Building and TS Coil Modules

CD-3c Everything Else....

