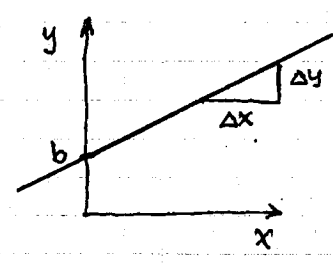


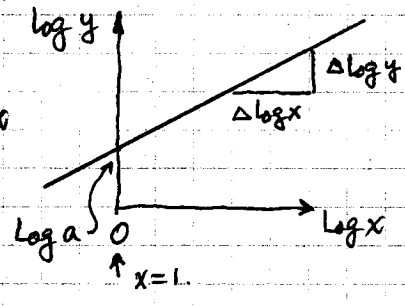
# GRAPHS

1) Linear relations:  $y = mx + b$



$\frac{\Delta y}{\Delta x} = m$  (slope)  
positive or negative.

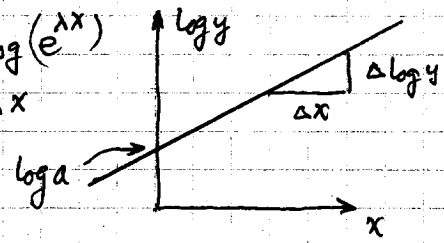
2) Power law:  $y = ax^m$   
 $\log y = \log a + m \log x$



$\frac{\Delta \log y}{\Delta \log x} = m$  (slope)  
positive or negative  
(log-log plot)

3) Exponential:  $y = ae^{\lambda x}$

$\log y = \log a + \log(e^{\lambda x})$   
 $= \log a + \lambda x$



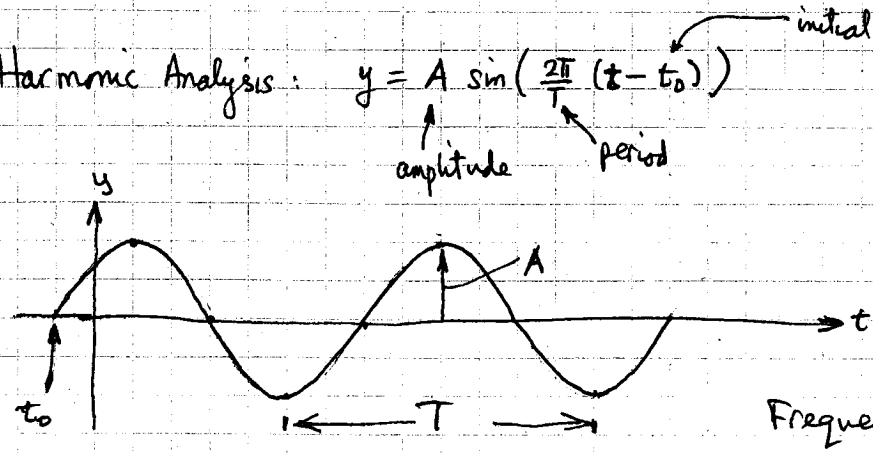
$\frac{\Delta \log y}{\Delta x} = \lambda$  (slope)  
positive or negative  
(semi-log plot)

If  $\frac{y_2}{y_1} = 2 = \frac{ae^{\lambda x_2}}{ae^{\lambda x_1}} = e^{\lambda(x_2 - x_1)}$   
 $x_2 - x_1 = \frac{.69}{\lambda}$

$\log 2 = \lambda(x_2 - x_1)$   
 $= .69$

If  $x$  is time,  $t_2 - t_1 = \frac{.69}{\lambda} =$  doubling time ( $y(t_2) = 2 \cdot y(t_1)$ )  
if  $\lambda$  is positive  
 $=$  half-life ( $y(t_2) = \frac{1}{2} y(t_1)$ )  
if  $\lambda$  is negative.

4) Harmonic Analysis:  $y = A \sin\left(\frac{2\pi}{T}(t - t_0)\right)$



Frequency  $f = \frac{1}{T}$

# Probability & Statistics

Let the probability that  $x_1 \leq x \leq x_2$  be  $\int_{x_1}^{x_2} P(x) dx$   
 $\uparrow$  probability density

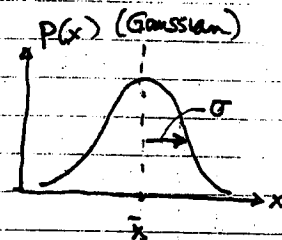
Normalization:  $1 = \int_{-\infty}^{\infty} P(x) dx$

$\bar{x} = \int_{-\infty}^{\infty} x P(x) dx$  (mean of  $x$ )

$\overline{(x-\bar{x})} = \int_{-\infty}^{\infty} (x-\bar{x}) P(x) dx = \bar{x} - \bar{x} \int_{-\infty}^{\infty} P(x) dx = \bar{x} - \bar{x} = 0$

$\overline{(x-\bar{x})^2} = \int_{-\infty}^{\infty} (x-\bar{x})^2 P(x) dx = \int_{-\infty}^{\infty} (x^2 - 2x\bar{x} + \bar{x}^2) P(x) dx = \overline{x^2} - 2\bar{x}\bar{x} + \bar{x}^2$   
 $= \overline{x^2} - \bar{x}^2$  mean square deviation.

$\sigma$  (standard deviation)  $= \sqrt{\overline{(x-\bar{x})^2}}$  = r.m.s. deviation  
 root mean square



If  $x, y$  are independent of each other  $P(x, y) = P_x(x) P_y(y)$ .

Normalization:  $1 = \int P(x, y) dx dy = \int P_x(x) dx \int P_y(y) dy = 1 \cdot 1$

Let  $z = ax + by$   
 $\uparrow$  constants

$\bar{z} = \int P(x, y) z dx dy = \int P_x(x) P_y(y) (ax + by) dx dy$   
 $= a \int P_x(x) x dx \int P_y(y) dy + b \int P_x(x) dx \int P_y(y) y dy = a\bar{x} + b\bar{y}$

$\overline{(z-\bar{z})^2} = \overline{z^2} - \bar{z}^2 = \int (ax+by)^2 P(x, y) dx dy - a^2\bar{x}^2 - b^2\bar{y}^2 - 2ab\bar{x}\bar{y}$   
 $= a^2\overline{x^2} + b^2\overline{y^2} + 2ab\bar{x}\bar{y} - a^2\bar{x}^2 - b^2\bar{y}^2 - 2ab\bar{x}\bar{y}$   
 $= a^2(\overline{x^2} - \bar{x}^2) + b^2(\overline{y^2} - \bar{y}^2) = a^2\sigma_x^2 + b^2\sigma_y^2 = \sigma_z^2$

Suppose  $z = \frac{1}{n}x + \frac{1}{n}x + \dots + \frac{1}{n}x$  where the  $x$ 's are  $n$  independent samples from the same population

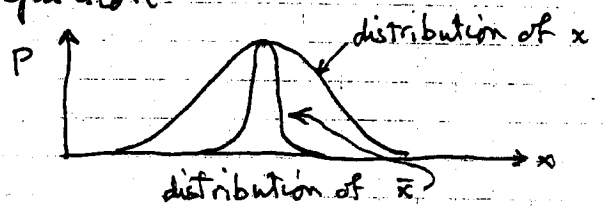
Then  $\bar{z} = n \cdot \frac{1}{n}\bar{x} = \bar{x}$

$\overline{(z-\bar{z})^2} = n \cdot \frac{1}{n^2}\sigma_x^2 = \frac{\sigma_x^2}{n}$

$\sigma_z = \frac{\sigma_x}{\sqrt{n}}$  ← std. dev. of original population

std. dev. of a population consisting of the mean of a sample of  $n$  members

This is why the mean of a sample is a more reliable measure of the mean of the population than an individual member of the population



More generally, suppose  $z = f(x, y)$ .

Given  $\bar{x}, \bar{y}, \sigma_x, \sigma_y$ , find  $\bar{z}, \sigma_z$

Assume  $\sigma_x \ll \bar{x}, \sigma_y \ll \bar{y}$  so that  $x$  stays near  $\bar{x}$ ,  $y$  stays near  $\bar{y}$

Do a Taylor expansion of  $f(x, y)$  around  $x = \bar{x}, y = \bar{y}$ :

$$z = f(\bar{x}, \bar{y}) + (x - \bar{x}) \frac{\partial f}{\partial x}(\bar{x}, \bar{y}) + (y - \bar{y}) \frac{\partial f}{\partial y}(\bar{x}, \bar{y}) + \dots$$

$$\bar{z} = \overbrace{f(\bar{x}, \bar{y})}^{f(\bar{x}, \bar{y})} + \underbrace{(\bar{x} - \bar{x})}_{0} \frac{\partial f}{\partial x}(\bar{x}, \bar{y}) + \underbrace{(\bar{y} - \bar{y})}_{0} \frac{\partial f}{\partial y}(\bar{x}, \bar{y}) = f(\bar{x}, \bar{y}) = \bar{z}$$

$$\text{Then } z - \bar{z} = (x - \bar{x}) \frac{\partial f}{\partial x}(\bar{x}, \bar{y}) + (y - \bar{y}) \frac{\partial f}{\partial y}(\bar{x}, \bar{y})$$

$$\sigma_z^2 = \overline{(z - \bar{z})^2} = \overline{(x - \bar{x})^2 \left[ \frac{\partial f}{\partial x}(\bar{x}, \bar{y}) \right]^2} + \overline{(y - \bar{y})^2 \left[ \frac{\partial f}{\partial y}(\bar{x}, \bar{y}) \right]^2} \quad \text{if } x - \bar{x}, y - \bar{y} \text{ are uncorrelated.}$$

$$\sigma_z^2 = \left[ \frac{\partial f}{\partial x}(\bar{x}, \bar{y}) \right]^2 \sigma_x^2 + \left[ \frac{\partial f}{\partial y}(\bar{x}, \bar{y}) \right]^2 \sigma_y^2$$

Example:  $F = ma$ . Relate  $\bar{F}, \sigma_F$  to  $\bar{m}, \sigma_m, \bar{a}, \sigma_a$

$$\bar{F} = \bar{m} \bar{a}$$

$$\frac{\partial F}{\partial m}(\bar{m}, \bar{a}) = \bar{a}, \quad \frac{\partial F}{\partial a}(\bar{m}, \bar{a}) = \bar{m}$$

$$\sigma_F^2 = \left[ \frac{\partial F}{\partial m}(\bar{m}, \bar{a}) \right]^2 \sigma_m^2 + \left[ \frac{\partial F}{\partial a}(\bar{m}, \bar{a}) \right]^2 \sigma_a^2 = \bar{a}^2 \sigma_m^2 + \bar{m}^2 \sigma_a^2$$

$$\left( \frac{\sigma_F}{\bar{F}} \right)^2 = \left( \frac{\sigma_m}{\bar{m}} \right)^2 + \left( \frac{\sigma_a}{\bar{a}} \right)^2$$

Populations are usually characterized by two numbers:  
a mean value  $\bar{x}$  (usually the arithmetic mean,

$$\frac{\sum_{i=1}^n x_i}{n}$$

and a standard deviation  $\sigma$

$$\sigma = \sqrt{(x - \bar{x})^2}$$

(also called the r.m.s (root-mean-square) deviation)

In general,  $\bar{x}$  and  $\sigma$  are independent parameters. However, for one particular distribution, the Poisson distribution

$$P(n) = e^{-\mu} \frac{\mu^n}{n!} \quad (n = 0, 1, 2, \dots)$$

it is easy to show that  $\bar{n} = \sum_n n P(n) = \mu$

$$\sigma = \sqrt{(\bar{n} - \bar{n})^2} = \sqrt{(\bar{n} - \mu)^2} = \sqrt{\mu} = \sqrt{\bar{n}}$$

Thus for a Poisson distribution, both the mean and standard deviation are determined by the single parameter  $\mu$ .

Application to counting statistics: If the probability of a count occurring in infinitesimal time  $dt$  is  $\lambda dt$ , then the probability of  $n$  counts occurring in time  $T$  is  $P(n) = e^{-\mu} \frac{\mu^n}{n!}$ , with  $\mu = \lambda T$ .

Since  $\sigma = \sqrt{n}$ ,  $\frac{\sigma}{\bar{n}}$  (fractional uncertainty) =  $\frac{\sqrt{n}}{n} = \frac{1}{\sqrt{n}}$

Example:  $\bar{n} = 10,000$  counts,  $\sigma = 100$  counts,  $\frac{\sigma}{\bar{n}} = \frac{1}{100} = 1\%$

Example: For reaction A,  $N_A = 1000$  counts are detected in a certain time  
 " " B,  $N_B = 600$  " " " " The same "

What is The fractional uncertainty of  $N_A - N_B = \Delta$

$$\sigma_{\Delta}^2 = \sigma_A^2 + \sigma_B^2 = 1000 + 600 = 1600, \quad \sigma_{\Delta} = 40, \quad \Delta = 1000 - 600 = 400$$

$$\frac{\sigma_{\Delta}}{\Delta} = \frac{40}{400} = \frac{1}{10} = 10\%$$

Example: 5 independent measurements of a quantity yields a mean of 40 and a standard deviation of 4.0 ← for the population

How many additional measurements needed to determine the mean to 2%.

We need  $n$  such that  $\frac{\left(\frac{4}{\sqrt{n}}\right)}{40} \leftarrow \begin{array}{l} \text{standard deviation of} \\ \text{mean of } n. \end{array} = .02$   
 $40 \leftarrow \text{population mean}$

$$\frac{4}{\sqrt{n}} = .02 \times 40 = .8, \quad \frac{4}{.8} = 5 = \sqrt{n}$$

$n = 25$  measurements are need.

5 measurements have already been made.  
 20 additional measurements are needed.